



**Leveraging Applications of Formal Methods,  
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## Leveraging Applications of Formal Methods, Verification, and Validation: International Workshops, SARS 2011 and MLSC 2011, held under the auspices of ... in Computer and Information Science)

This volume contains a selection of revised papers that were presented at the Software Aspects of Robotic Systems, SARS 2011 Workshop and the Machine Learning for System Construction, MLSC 2011 Workshop, held during October 17-18 in Vienna, Austria, under the auspices of the International Symposium Series on Leveraging Applications of Formal Methods, Verification, and Validation, ISoLA. The topics covered by the papers of the SARS and the MLSC workshop demonstrate the breadth and the richness of the respective fields of the two workshops stretching from robot programming to languages and compilation techniques, to real-time and fault tolerance, to dependability, software architectures, computer vision, cognitive robotics, multi-robot-coordination, and simulation to bio-inspired algorithms, and from machine learning for anomaly detection, to model construction in software product lines to classification of web service interfaces. In addition the SARS workshop hosted a special session on the recently launched KOROS project on collaborating robot systems that is borne by a consortium of researchers of the faculties of architecture and planning, computer science, electrical engineering and information technology, and mechanical and industrial engineering at the Vienna University of Technology. The four papers devoted to this session highlight important research directions pursued in this interdisciplinary research project.

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